F, 09/20/19

### Fall'19 CSCE 629

## Analysis of Algorithms

## Fang Song Texas A&M U

## Lecture 9

- Topological sort cont'd
- Dynamic programming

Credit: based on slides by K.Wayne

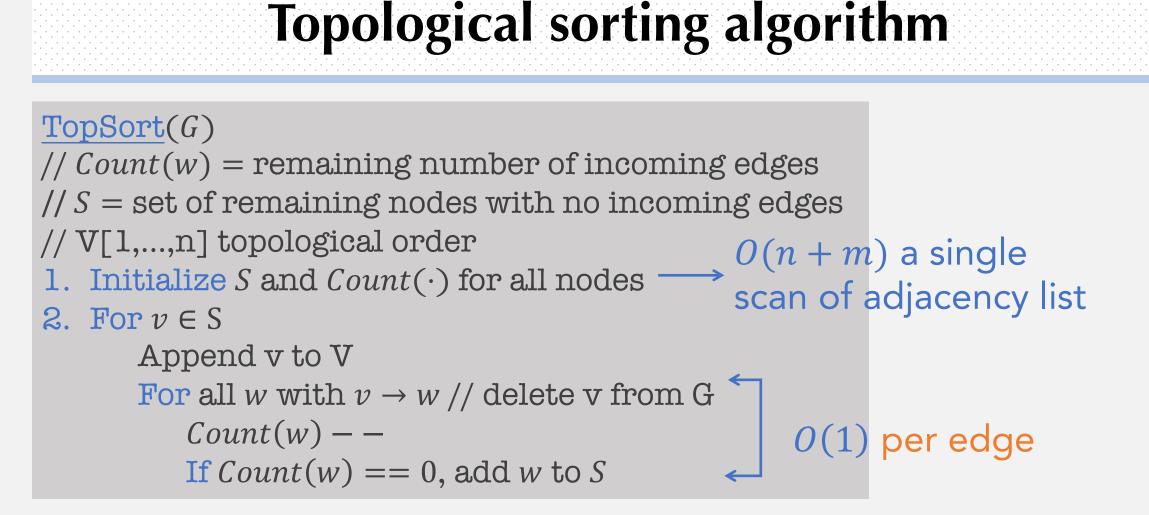
1. Does every DAG have a topological order? Lemma1. A DAG *G* has a node with no entering edges.

Corollary. If G is a DAG, then G has a topological order.

Proof (of corollary) given Lemma1. [by induction]

- Base case: true if n = 1.
- Given DAG on n > 1 nodes, find a node v with no entering edges [Lemma1]
- $G \{v\}$  is a DAG, since deleting v cannot create cycles.
- By inductive hypothesis,  $G \{v\}$  has a topological ordering.
- Place v first; then append nodes of  $G \{v\}$  in topological order. [valid because v has no entering edges]





Theorem. TopSort computs a topological order in O(n + m) time

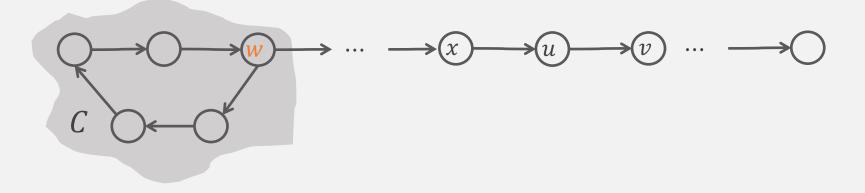
#### Lemma1. A DAG G has a node with no entering edges.

#### Proof. [by contradiction]

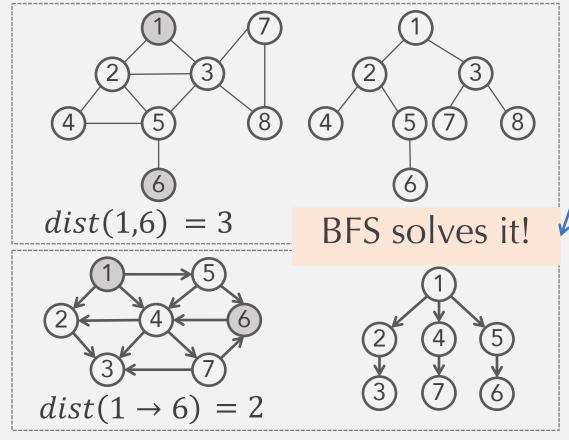
- Suppose G is a DAG, and every node has at least one entering edge.
- Pick any node v, and follow edges backward from v. Repeat till we visit a node, say w twice. ( $v \leftarrow u \leftarrow x \cdots \leftarrow w \cdots \leftarrow w$ )

**Completing the argument** 

- Let C be the sequence of nodes between successive visits to w.
- $\rightarrow$  C is a cycle! Contradiction!



# Input: graph G, nodes s and t. Output: dist(s,t)



#### Weighted graphs

- Every edge has a length  $l_e$
- Length of a path  $l(P) = \sum_{e \in P} l_e$
- Distance  $dist(u, v) = \min_{P:u \sim v} l(P)$

#### $\forall e \in E, l_e = 1$

Shortest path in a graph

#### Length function $l: E \to \mathbb{Z}$

- $l(u, v) = \infty$  if not an edge
- Model time, distance, cost ...
- Can be negative, e.g., fund transfer, heat in chemistry reaction ...

How to solve weighted case?

Shortest path in DAGs  
• Input: DAG G, length l, nodes s and t  
• Output: 
$$d(t) := dist(s, t)$$
  
// Initialize all  $d(\cdot) = \infty$   
1.  $d(s) = 0$   
2. For  $v \in V \setminus \{v\}$  in topological order  
 $d(v) = \min_{(u,v) \in E} \{d(u) + l(u,v)\}$   
• Neduce to subproblems  $d(6), d(5), ...$   
• Subproblems overlap: e.g. both  $d(6), d(5)$   
involve  $d(2)$   
• An ordering of subproblems (DAG: edges go left to right)  
•  $d(t) = topological order definition of the state of t$ 

#### Dynamic Programming. Break up a problem into a series of overlapping subproblems; combine solutions to smaller subproblems to form solution to large subproblem.

Algorithm design arsenal

An implicit DAG: nodes=subproblems, edges = dependencies

 Divide-&-Conquer. Break up a problem into independent (typically significantly smaller) subproblems; combine solutions to subproblems to form solution to original problem. Input: a sequence of numbers a<sub>1</sub>, ..., a<sub>n</sub>
Output: a longest increasing subsequence a<sub>i1</sub>, ..., a<sub>ik</sub>

•  $a_{i_1} < a_{i_2} < \dots < a_{i_k} \ (1 \le i_1, \dots, i_k \le n)$ 

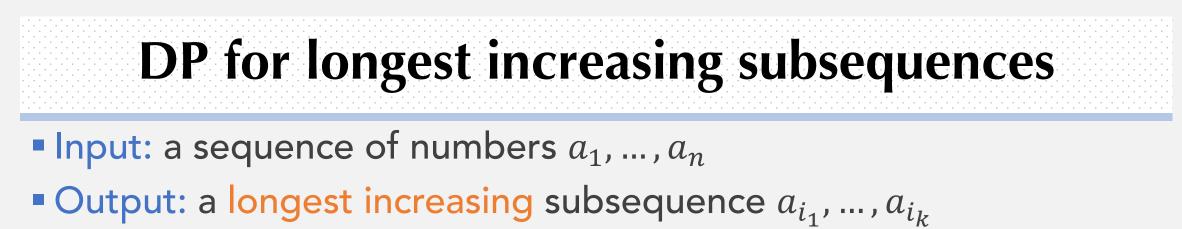


#### Brute-force algorithm

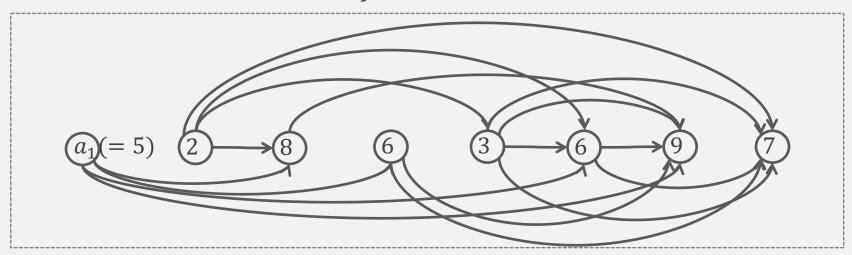
• For each  $1 \le k \le n$ , check if exists an increasing subsequence of length k

Longest increasing subsequences

• Ω(2<sup>*n*</sup>) ...



Form a DAG G: if  $a_i \leq a_j$ , add an edge  $i \rightarrow j$ 



Increasing subsequence ⇔ path in *G* → Reduced to finding a **longest** path in the DAG!

9

## Longest increasing subsequences/longest path Input: a sequence of numbers $a_1, \dots, a_n$ • Output: a longest increasing subsequence $a_{i_1}, \ldots, a_{i_k}$ // Initialize all L(j) = 1; length of longest path ending at j 1. For j = 1, 2, ..., n $L(j) = 1 + \max\{L(i): (i, j) \in E\}$ 2. Return max L(j)

- Running time:  $O(n+m) = O(n^2)$ 
  - What is the worst case?
- Can you output the subsequence?

#### **Recap on DP**

There is an ordering on the subproblems, and a relation showing how to solve a subproblem given answers to "smaller" subproblems (i.e., those appear earlier in the ordering)

## **Dynamic Programming history**

## Richard Bellman

- DP [1953]
- B-Ford alg. for general shortest path (stay tuned!),
- Curse of dimensionality...

### Etymology

- Dynamic programming = planning over time
- Secretary of Defense was hostile to mathematical research
- Bellman sought an impressive name to avoid confrontation

"it's impossible to use dynamic in a pejorative sense" "something not even a Congressman could object to" Reference: Bellman, R. E. Eye of the Hurricane, An Autobiography.



#### THE THEORY OF DYNAMIC PROGRAMMING

RICHARD BELLMAN

1. Introduction. Before turning to a discussion of some representative problems which will permit us to exhibit various mathematical features of the theory, let us present a brief survey of the fundamental concepts, hopes, and aspirations of dynamic programming.

To begin with, the theory was created to treat the mathematical problems arising from the study of various multi-stage decision processes, which may roughly be described in the following way: We have a physical system whose state at any time t is determined by a set of quantities which we call state parameters, or state variables.

#### Indispensable technique for optimization problems

**Dynamic Programming applications** 

Many solutions, each has a value Goal: a solution w. optimal (min or max) value

#### Areas

- Computer science: theory, graphics, AI, compilers, systems, ...
- Bioinformatics
- Operations research, information theory, control theory

#### Some famous DP algorithms

- Avidan–Shamir for seam carving
- Unix diff for comparing two files
- Viterbi for hidden Markov models
- Knuth–Plass for word wrapping text in TeX.
- Cocke–Kasami–Younger for parsing context-free grammars