

# Graph Algorithms

Andreas Klappenecker

# Graphs

A **graph** is a set of **vertices** that are pairwise connected by **edges**.

We distinguish between **directed** and **undirected** graphs.

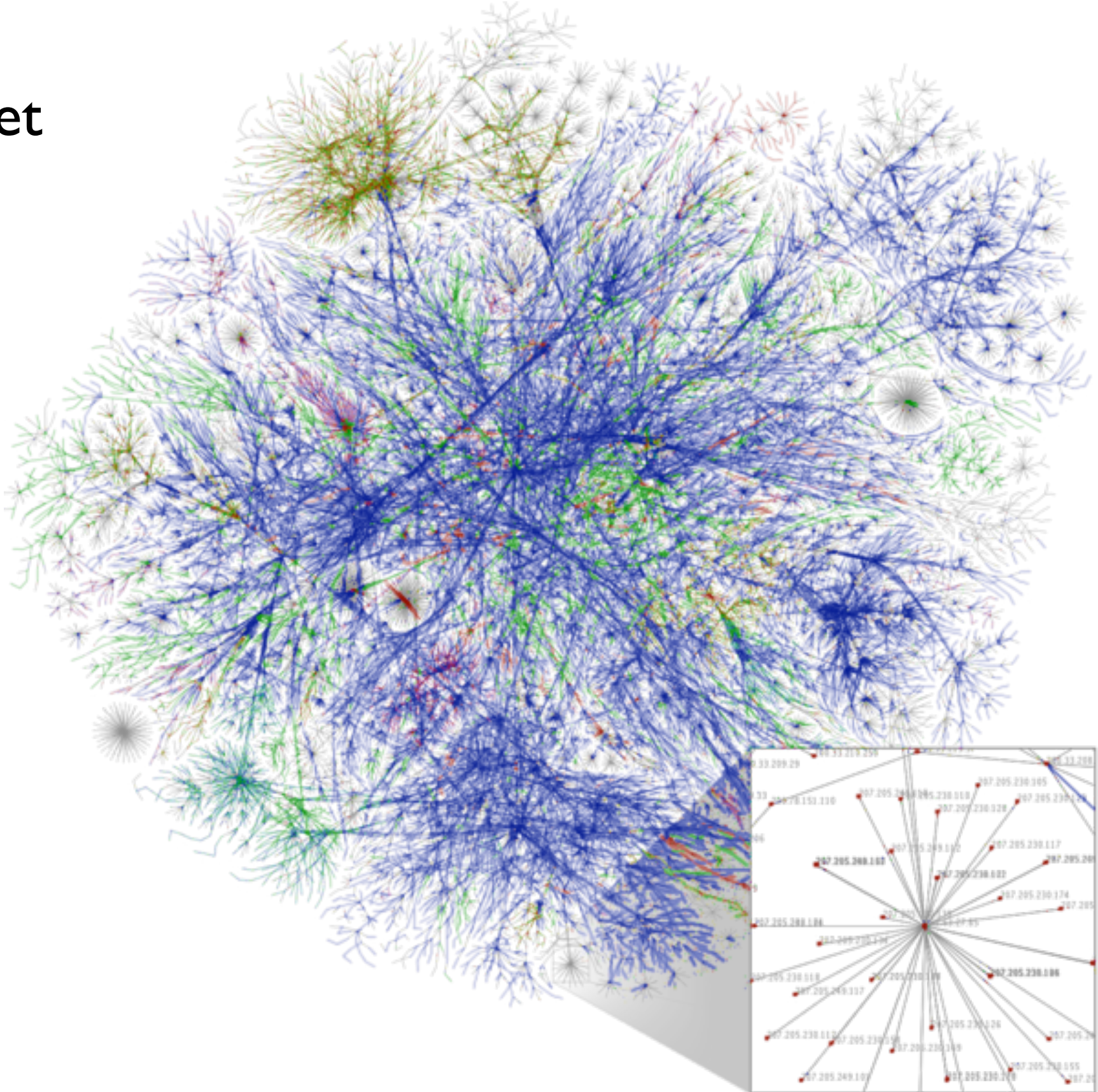
Why are we interested in graphs?

- Graphs are a very useful abstraction
- Graphs have many interesting applications
- Thousands of graph algorithms are known

# Versatile Abstraction

Application	Vertices	Edges
Traffic	Intersections	Roads
Social Network	People	Friendship
Internet	Class C network	Connection
Game	Board Position	Legal Move
Erdos number	People	Coauthored Paper
CMOS Circuits	FET, Vdd, Vss, I/O	Wires
Financial	Stock, Currency	Transactions
Programs	Procedures	Procedure Call f->g

# The Internet



# Undirected Graphs

An **undirected graph** is a pair  $G=(V,E)$ , where

- $V$  is a finite set
- $E$  is a subset of  $\{ e \mid e \subseteq V, |e|=2 \}$ .

The elements in  $V$  are called **vertices**.

Elements in  $E$  are called **edges**, e.g.  $e=\{u,v\}$ , written  $e=(u,v)$ .

Self-loops are not allowed for undirected graphs,  $e \neq \{u,u\} = \{u\}$ .

# Directed Graphs

An **directed graph** is a pair  $G=(V,E)$ , where

- $V$  is a finite set
- $E$  is a subset of  $V \times V$

The set of edges does not need to be symmetric.

Thus, if  $(u,v)$  is an edge, then  $(v,u)$  does not need to be an edge.

We illustrate a directed edge often by an arrow  $u \rightarrow v$ .

# Graph Terminology

If  $e=(u,v)$  is an edge in a graph, then  $v$  is called **adjacent** to  $u$ .

For undirected graphs, adjacency is a symmetric relation.

The edge  $e$  is said to be **incident** to  $u$  and  $v$ .

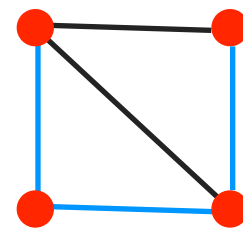
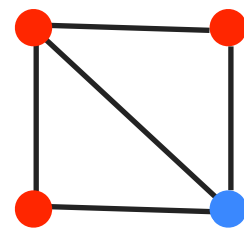
The number of edges incident to a vertex is called the **degree** of the vertex.

# Graph Terminology

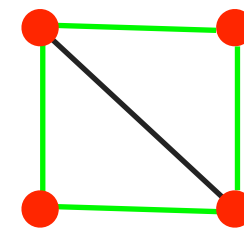
A **path** is a sequence of vertices that are connected by edges.

A **cycle** is a path whose first and last vertices are the same.

Two vertices are **connected** if and only if there is a path between them.



path



cycle



# Breadth-First Search

# Breadth First Search (BFS)

Input: A graph  $G = (V, E)$  and source node  $s$  in  $V$

mark all nodes  $v$  in  $V$  as unvisited

mark source node  $s$  as visited

enq(Q,s) // first-in first-out queue Q

while (Q is not empty) {

$u := \text{deq}(Q);$

    for each unvisited neighbor  $v$  of  $u$  {

        mark  $v$  as visited; enq(Q,v);

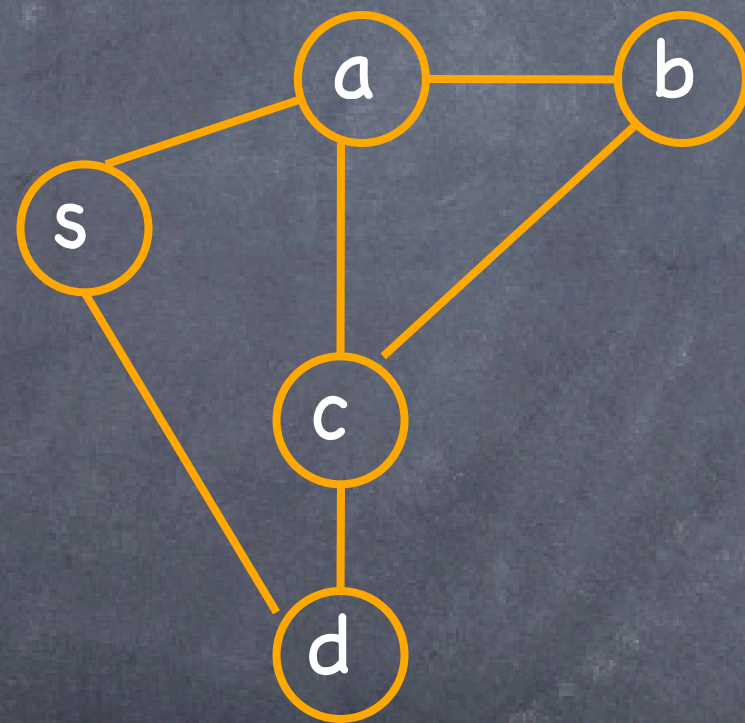
    }

}

# Example

demo-bfs

# BFS Example



Visit the nodes in the order:

s

a, d

b, c

# BFS Tree

We can make a spanning tree rooted at the source node  $s$  by remembering the parent of each node.

# Breadth First Search (BFS)

Input: A graph  $G = (V, E)$  and source node  $s$  in  $V$

mark all nodes  $v$  in  $V$  as unvisited; set  $\text{parent}[v] := \text{nil}$  for all  $v$  in  $V$

mark source node  $s$  as visited;  $\text{parent}[s] := s$ ;

$\text{enq}(Q, s)$  // first-in first-out queue  $Q$

while ( $Q$  is not empty) {

$u := \text{deq}(Q)$ ;

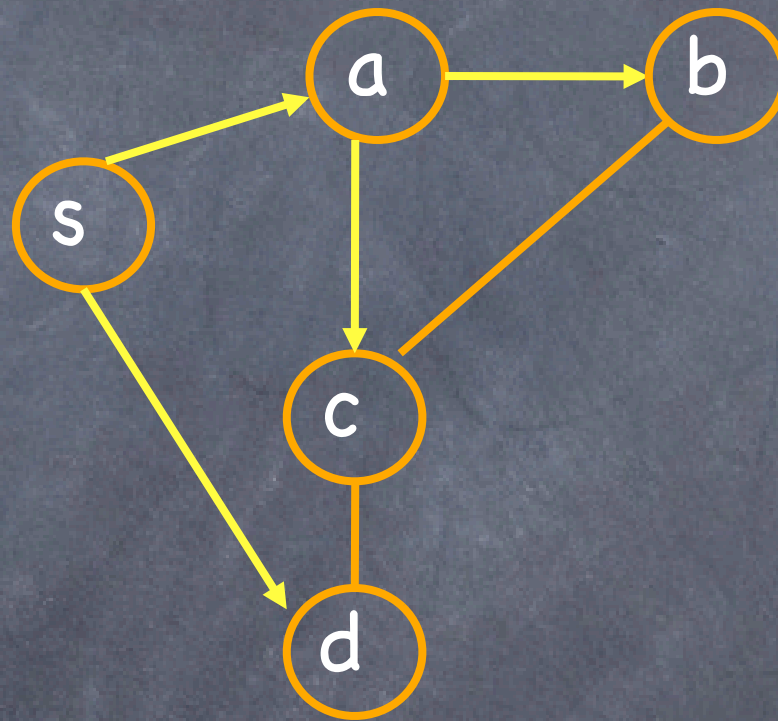
    for each unvisited neighbor  $v$  of  $u$  {

        mark  $v$  as visited;  $\text{enq}(Q, v)$ ;  $\text{parent}[v] := u$

    }

}

# BFS Tree Example



# BFS Trees

The BFS tree is in general **not unique** for a given graph. It depends on the order in which neighboring nodes are processed.



# BFS Numbering

During the breadth-first search, assign to each node  $v$  its distance  $d[v]$  from the source.

# Breadth First Search (BFS)

Input: A graph  $G = (V, E)$  and source node  $s$  in  $V$

mark all nodes  $v$  in  $V$  as unvisited; set  $\text{parent}[v] := \text{nil}$ ;  $d[v] = \infty$  for all  $v$  in  $V$

mark source node  $s$  as visited;  $\text{parent}[s] := s$ ;  $d[s] = 0$

$\text{enq}(Q, s)$  // first-in first-out queue  $Q$

while ( $Q$  is not empty) {

$u := \text{deq}(Q)$ ;

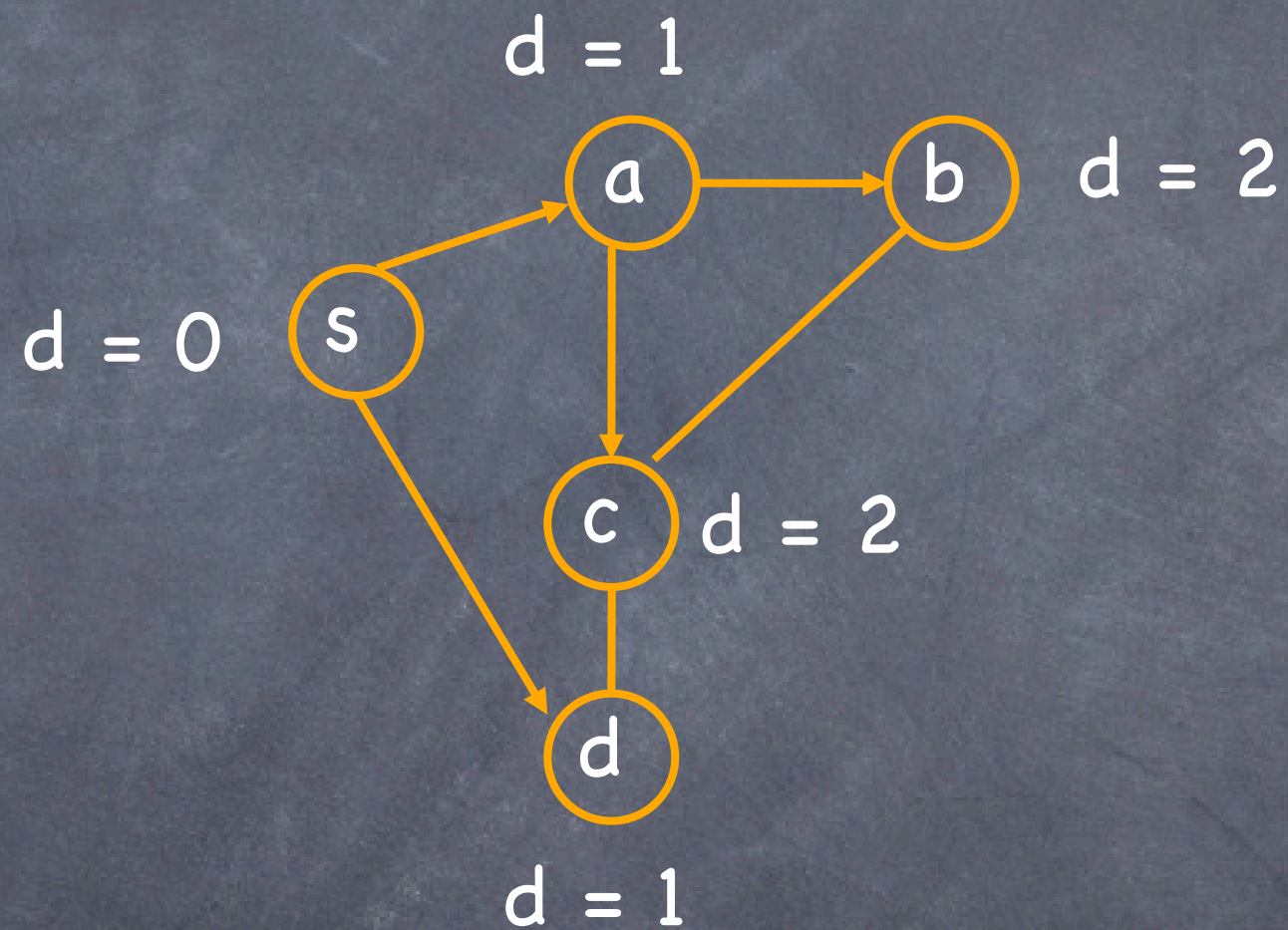
    for each unvisited neighbor  $v$  of  $u$  {

        mark  $v$  as visited;  $\text{enq}(Q, v)$ ;  $\text{parent}[v] := u$ ;  $d[v] = d[u] + 1$

    }

}

# BFS Numbering Example



# Shortest Path Tree

**Theorem:** The BFS algorithm

- visits all and only nodes reachable from  $s$
- for all nodes  $v$  sets  $d[v]$  to the shortest path distance from  $s$  to  $v$
- sets parent variables to form a shortest path tree

# Proof Ideas

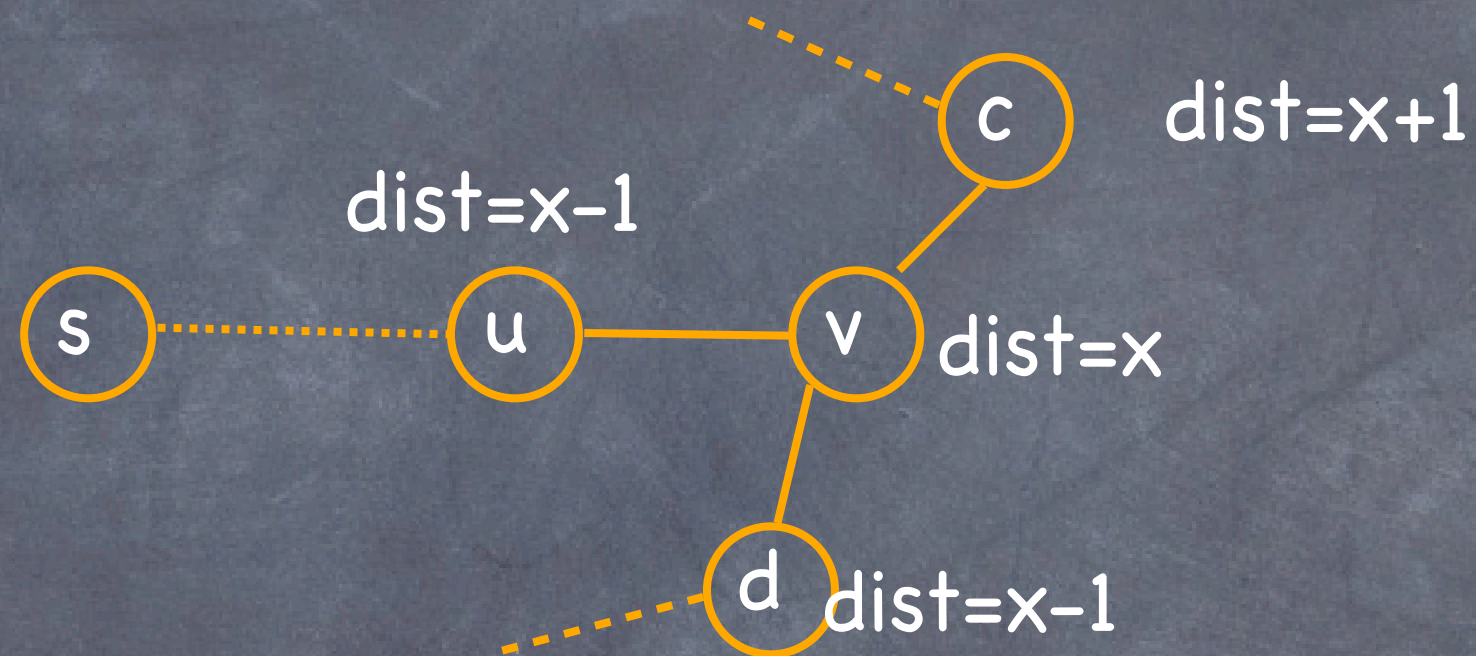
We use induction on the distance from the source node  $s$  to show that a node  $v$  at distance  $x$  from  $s$  has correct  $d[v]$ .

**Basis:** Distance 0.  $d[s]$  is set to 0.

**Induction:** Assume that all nodes  $u$  at distance  $x-1$  from  $s$  satisfy  $d[u]=x-1$ . Our goal is to show that every node  $v$  at distance  $x$  satisfies  $d[v]=x$  as well.

Since  $v$  is at distance  $x$ , it has at least one neighbor at distance  $x-1$ . Let  $u$  be the first of these neighbors that is enqueued.

# Proof Ideas



A key property of shortest path distances: If  $v$  has distance  $x$ ,

- it must have a neighbor with distance  $x-1$ ,
- no neighbor has distance less than  $x-1$ , and
- no neighbor has distance more than  $x+1$

# Proof Ideas

**Claim:** When the node  $u$  is dequeued, then  $v$  is still unvisited.

Indeed, this follows from behavior of the queue and the fact that  $d$  never underestimates the distance.

By induction,  $d[u] = x-1$ .

When  $v$  is enqueued,  $d[v]$  is set to  $d[u] + 1 = x$ .

# BFS Running Time

Initialization of each node takes  $O(V)$  time

Every node is enqueued once and dequeued once, taking  $O(V)$  time

When a node is dequeued, all its neighbors are checked to see if they are unvisited, taking time proportional to number of neighbors of the node, and summing to  $O(E)$  over all iterations

Total time is  $O(V+E)$



# Credits

In the preparation of these slides, I got inspired by slides by Robert Sedgewick. The slides on BFS are based on slides by Jennifer Welch.