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Fall'19 CSCE 629

# Analysis of Algorithms

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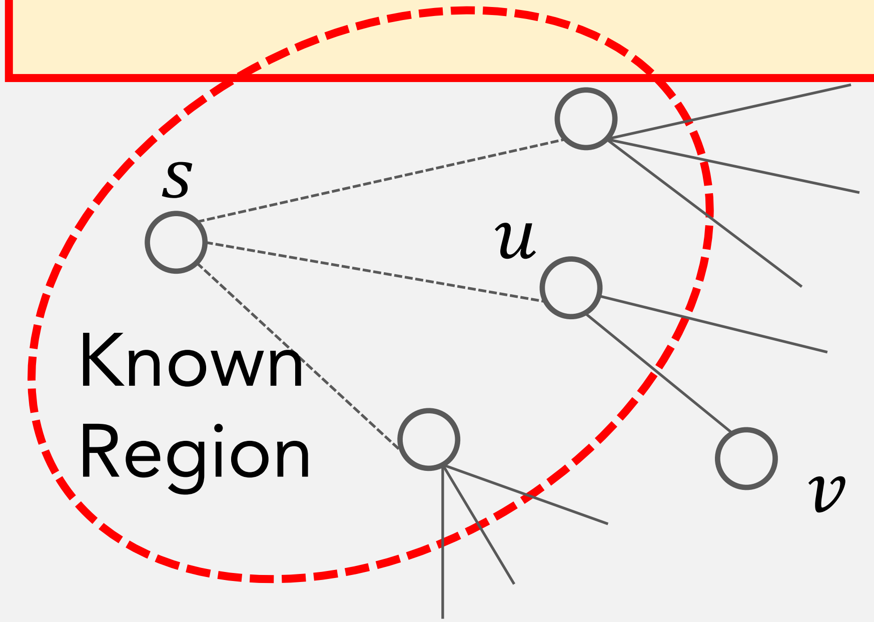
## Lecture 15

- Dijkstra's algorithm cont'd
- Interval scheduling

# Reflection on Dijkstra: greedy stays ahead

- Known region R: in which the shortest distance to $s$ is known
- Growing R: adding $v$ that has the shortest distance to $s$
- How to Identify $v$? The one that minimizes $d(u) + l(u, v)$ for $u \in R$

Shortest path to some $u$ in known region, followed by a single edge $(u, v)$




***Dijk***$(G, s)$ // initialize $d(s) = 0$, $d(u) = \infty$ , R=∅
While R $\neq V$
    Pick $v \notin R$ w. smallest $d(v)$ // by Priority Q
    Add $v$ to $R$
    For all edges $(v, w) \in E$
    If $d(v) > d(u) + l(u, v)$
        $d(v) \leftarrow d(u) + l(u, v)$

# Contrast with Bellman-Ford

- Dijkstra (Greedy) $O((m+n)\log n)$

$$d(v) = \min_{u \in R} d(u) + l(u,v)$$

- Positive weight: no need to wait; more edges in a path do not help

- Bellman-Ford (Dynamic programming) $O(mn)$

$$\mathrm{OPT}(i,v) = \min\left\{\mathrm{OPT}(i-1,v),\ \min_{v \to w \in E}\{\mathrm{OPT}(i-1,w) + l_{v \to w}\}\right\}$$

## ❖Global vs. Local

- Dijkstra's requires global information: known region & which to add
- Bellman-Ford uses only local knowledge of neighbors, suits distributed setting

# Network routing: distance-vector protocol

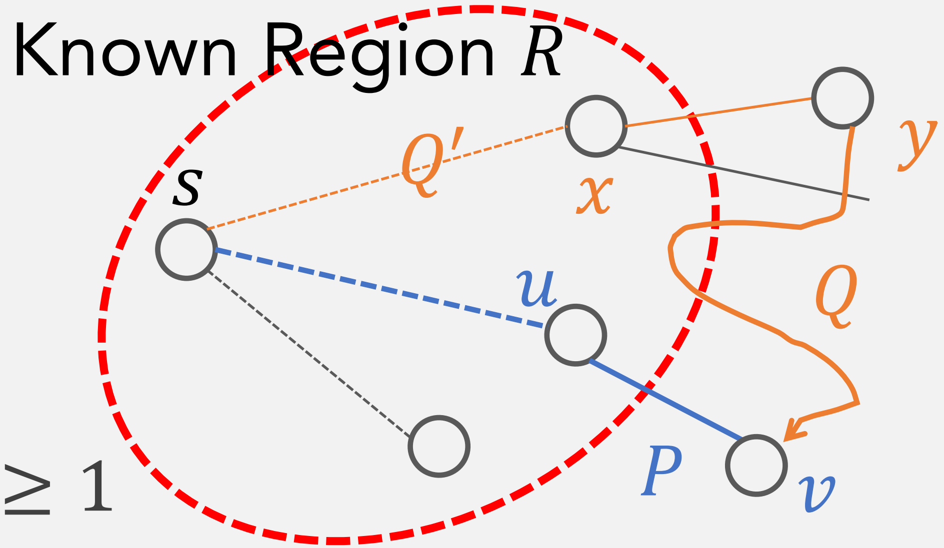
- Communication network
  - Nodes: routers
  - Edges: direct communication links
  - Cost of edge: delay on link.

naturally nonnegative, but Bellman-Ford used anyway!

- Distance-vector protocol ["routing by rumor"]
  - Each router maintains a vector of shortest-path lengths to every other node (distances) and the first hop on each path (directions).
  - Algorithm: each router performs separate computations for each potential destination node.
- Path-vector protocol: coping with dynamic costs

# Correctness of Dijkstra's algorithm

Invariant. For each node $u \in R$, $d(u)$ is the length of a shortest $s - u$ path

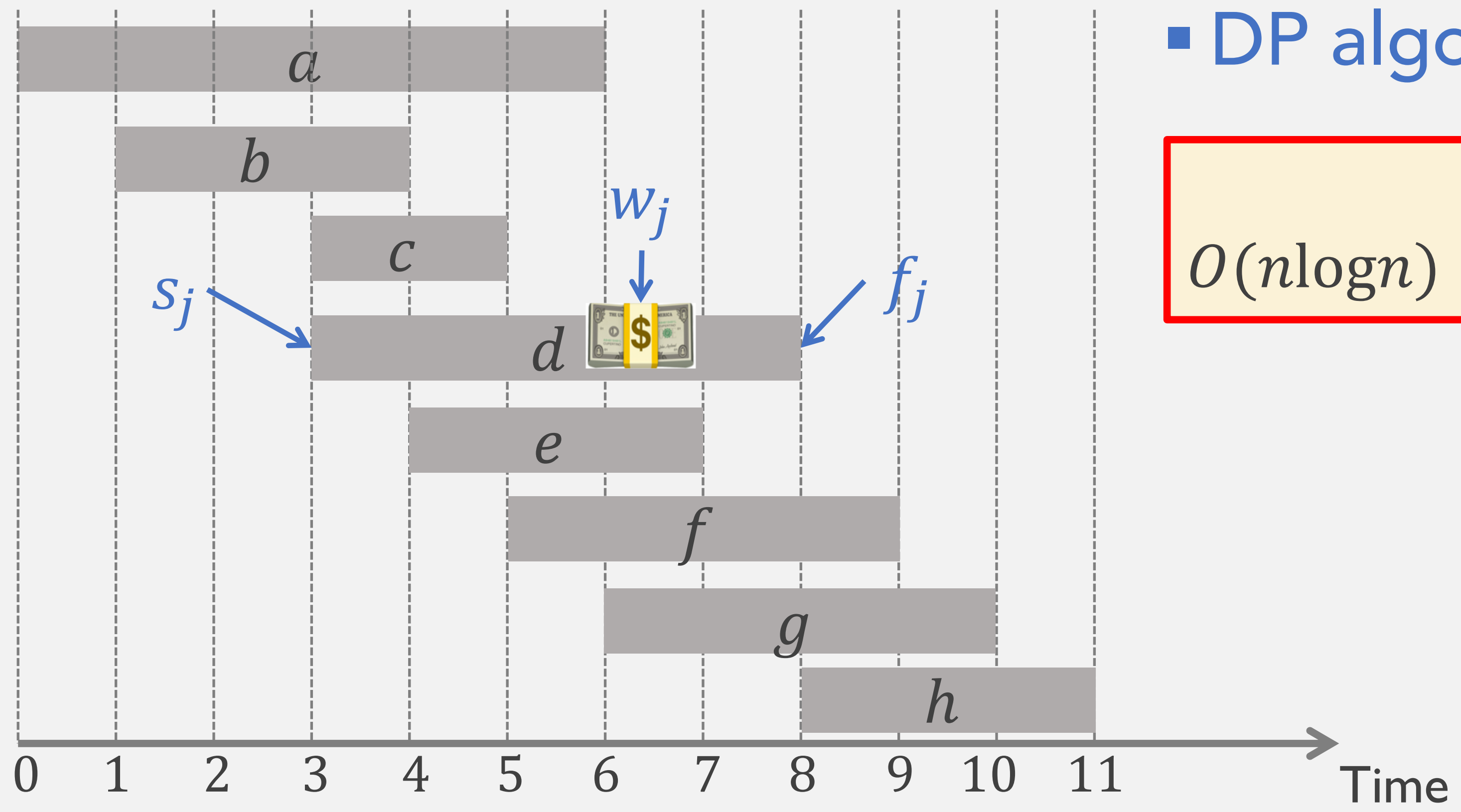



Proof. (By induction on size of R)

- Base case: $|R| = 1$ trivial
- Induction hypothesis: true for $|R| = k \geq 1$
  - Let $v$ be the next node added to $R$ and $(u, v)$ be the chosen edge. Call this $s - u - v$ path $P$.
  - Consider any $s - v$ path $Q$. [Next show it's no shorter than $P$]
  - Let $(x, y)$ be the first edge in $Q$ leaving $R$; let $Q'$ be the $s - x$ segment
  - $l(Q) \geq l(Q') + l(x, y) \geq d(x) + l(x, y) \geq l(P)$; because Dijkstra's picked $v$ in this iteration (node outside $R$ with shortest distance to $s$)

# Recall: weighted interval scheduling

- Input. $n$ jobs; job $j$ starts at $s_j$, finishes at $f_j$, weight $w_j$
- Output. Subset of mutually compatible jobs of maximum weight




- DP algorithm $O(n \log n)$

**Today**

$O(n\log n)$ Greedy algorithm for $w_j = 1$.

# Greedy strategies

Recall. DP recurrence. $\mathrm{OPT(j)}$ = value of optimal solution to jobs $1,2,\ldots,j$

$$\mathrm{OPT}(j) = \begin{cases} 0 & \text{if } j = 0 \\ \max\{\mathrm{OPT}(j-1), w_j + \mathrm{OPT}(pre(j))\} & \text{otherwise} \end{cases}$$

- Greedy: be lazy & pick the next compatible job that "looks nice"
  - Earliest start time: ascending order of $s_j$.
  - Earliest finish time: ascending order of $f_j$.
  - Shortest interval: ascending order of $f_j - s_j$.
  - Fewest conflicts: the one that conflicts the least number of jobs go first.
- Exercise. Find counterexamples for each strategy (if possible)

# Greedy: counterexamples

☹ Earliest start time:

☹ Shortest interval:

☹ Fewest conflicts:

☺ Earliest finishing time

# Greedy Algorithm: earliest finishing time

***IntScheduling*** $(\{s_j, f_j\})$

1. Sort by finishing time so that $f_1 \leq f_2 \leq \cdots \leq f_n$ → $O(n\log n)$
2. $A \leftarrow \emptyset$ // set of selected jobs
3. For $j = 1, \ldots, n$
   If $j$ compatible with A
   $A \leftarrow A \cup \{j\}$

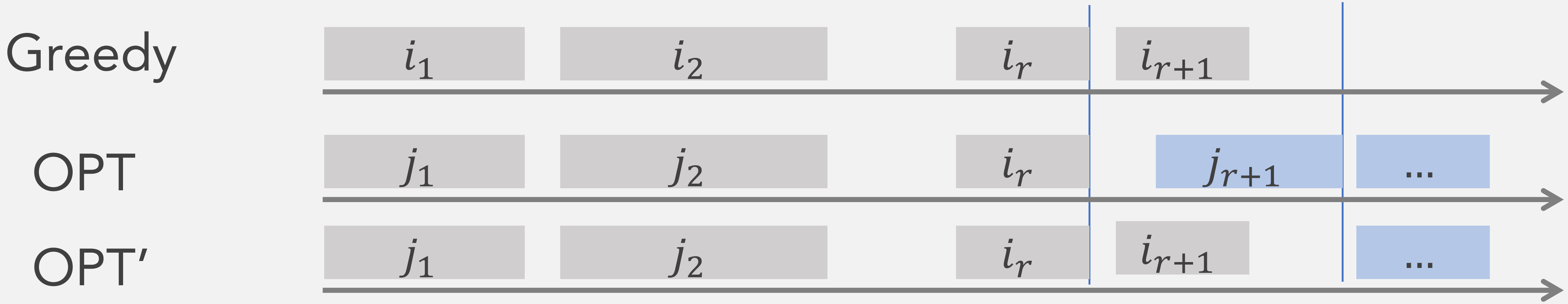
$n \times O(1)$

- Running time: $O(n \log n)$
- Correctness: proof by contradiction
  - Suppose greedy is not optimal
  - Consider an optimal strategy: one that agrees with Greedy for as many initial jobs as possible
  - Look at the first place that they differ: show a new optimal that agrees with greedy more

# Greedy Algorithm: correctness

Proof (by contradiction): Suppose greedy is not optimal

- Let $i_1, i_2, \dots, i_k$ denote set of jobs selected by greedy
- Let $j_1, j_2, \dots, j_m$ be set of jobs in the optimal solution OPT where $i_1 = j_1, i_2 = j_2, \dots, i_r = j_r$ for the largest possible value of $r$
- Sub $i_{r+1}$ for $j_{r+1}$ in OPT: still feasible and optimal (OPT'); but agrees with Greedy at $r + 1$ positions; contradicts the maximality of $r$



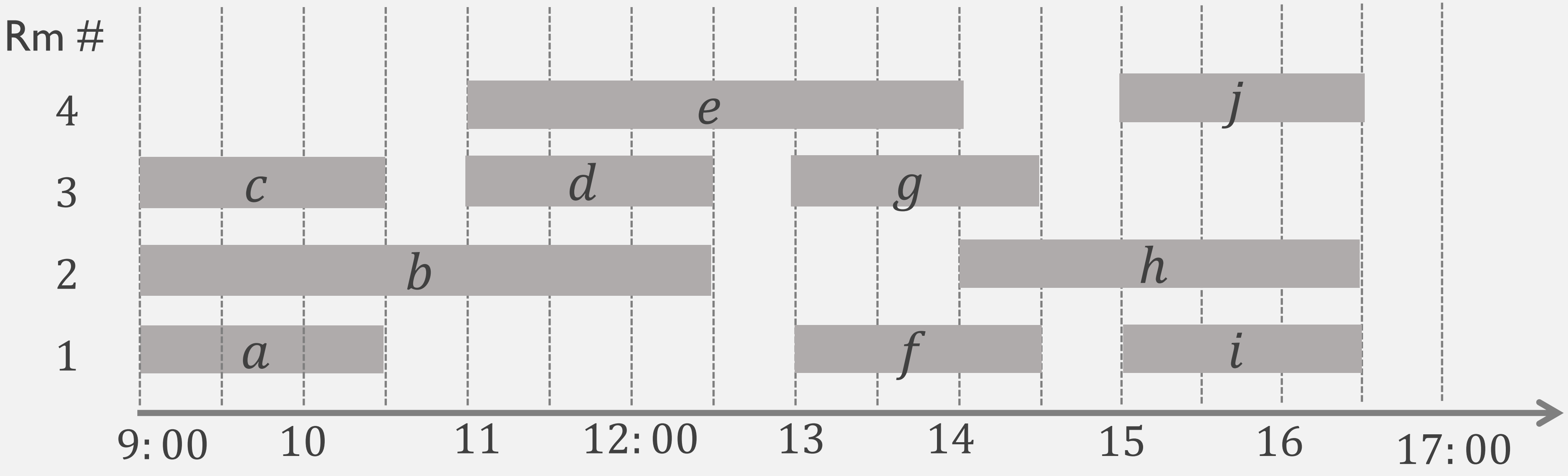
# Interval Partitioning Problem

Scheduling classes

- Input. Lectures $\{s_j, f_j\}$
- Output. Minimum number of classrooms to schedule all lectures so that no two occur at the same time in the same room.

Can you do better?

10 lectures scheduled in 4 classrooms

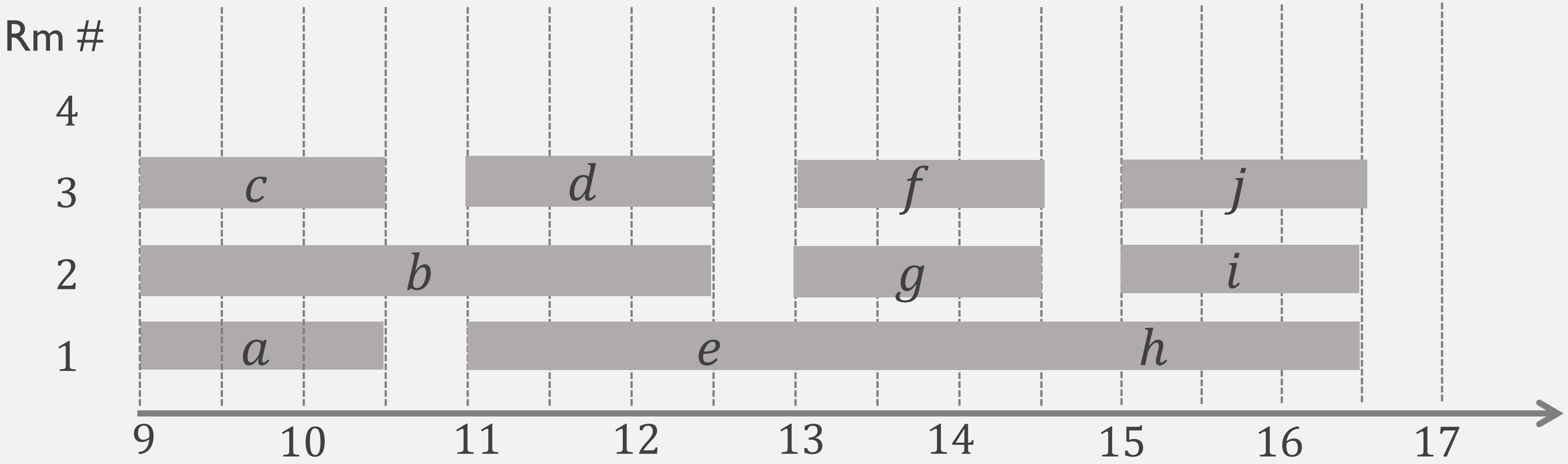


# Interval Partitioning Problem

## Scheduling classes

- Input. Lectures $\{s_j, f_j\}$
- Output. Minimum number of classrooms to schedule all lectures so that no two occur at the same time in the same room.

YES! 10 lectures scheduled in 3 classrooms



# Greedy algorithm

- Idea. Sort lectures in increasing order of start time: assign lecture to any compatible classroom.

***IntPartition***$(\{s_j, f_j\})$ // $r \leftarrow 0$ # of allocated rooms
1. Sort by starting time so that $s_1 \leq s_2 \leq \cdots \leq s_n$
2. For $j = 1, \dots, n$
   If $j$ compatible with some classroom $k$
      Schedule $j$ in room $k$
   Else allocate new classroom $r + 1$
      Schedule $j$ in room $r + 1$
      $r \leftarrow r + 1$

How to do it in $O(\log r)$

OBS. # rm needed $\geq$ depth of input intervals (i.e., Max. number of lectures that overlap)

- Running time. $O(n \log n)$
- Optimality. #Rm allocated = depth of input intervals